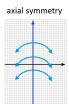
Introduction

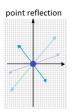
Spectral gaps for higher Laplacians and group cohomology

Piotr Mizerka

Institute of Mathematics of Polish Academy of Sciences

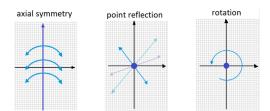
Noncommutative geometry: metric and spectral aspects, Kraków, 28 September 2022







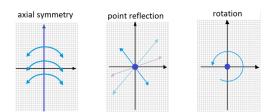
Introduction •00



• Generalization: symmetries must have fixed points

Introduction

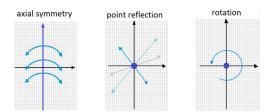
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- Generalization: symmetries must have fixed points
- An "isometric" fixed point property: Kazhdan's Property (T)

Introduction

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- An "isometric" fixed point property: Kazhdan's Property (T)
- (T) can be applied to construct expanders

Introduction

• Goal: study cohomological conditions generalizing property (T)



Introduction

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Laplacian spectral gaps

• The conditions: vanishing and reducibility of group cohomology

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- A criterion for vanishing and reducibility is provided by Laplacians
- Idea: interpretation in a group ring setting

Introduction

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• Vanishing and reducibility of cohomology and property (T)

Introduction

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Vanishing and reducibility of cohomology and property (T)

Laplacian spectral gaps

 Spectral gaps for higher Laplacians vs vanishing and reducibility

Introduction

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Vanishing and reducibility of cohomology and property (T)

Laplacian spectral gaps

- Spectral gaps for higher Laplacians vs vanishing and reducibility
- Fox calculus

- Vanishing and reducibility of cohomology and property (T)
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- Spectral gap for the first Laplacian of $SL_3(\mathbb{Z})$

Vanishing and reducibility of cohomology and property (T)

Laplacian spectral gaps









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- group cohomology measures e.g. group extensions
- one defines group cohomology for an arbitrary group module
- there are several ways to compute group cohomology
- one may use e.g. projective resolutions:

$$\mathcal{F} = \cdots F_n \to \cdots \to F_0 \to \mathbb{Z} \to 0$$
,

$$H^n(G, V) = H_n(\operatorname{Hom}_G(\mathcal{F}, V))$$

Introduction

Vanishing of cohomology and property (T)

vanishing = vanishing for every unitary representation

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Definition

Introduction

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 (T) ⇔ coninuous affine isometric actions on real Hilbert spaces have fixed points

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Theorem (Ozawa, 2014)

 $G = \langle s_1, \dots, s_n | \dots \rangle$ has property (T) iff there exists $\lambda > 0$ such that $\Delta_0^2 - \lambda \Delta_0 = \sum \xi_i^* \xi_i \ (\Delta_0 = d_0^* d_0 = \sum_{i=1}^n (1 - s_i)^* (1 - s_i)).$



• Bader and Nowak, 2020

Laplacian spectral gaps

Reducibility of cohomology

- Bader and Nowak, 2020
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Definition

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The *i*th reduced cohomology is defined by $\overline{H}' = \text{Ker } d_i / \overline{\text{Im } d_{i-1}}$. We say that the *i*th cohomology is reduced if H^i coincides with \overline{H}^i .

Reducibility vs vanishing

Introduction

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Proposition (Dymara-Januszkiewicz)

For any i > 2 there exists a group G_i with reduced H^i and $H^{i}(G, \rho_0) \neq 0$ for some unitary representation ρ_0 .

Introduction

Spectral gaps for higher Laplacians vs vanishing and reducibility

Introduction

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Definition

Introduction

 $M \in M_n(\mathbb{R}G)$ is an SOS if there exist M_1, \ldots, M_l such that

$$M = M_1^* M_1 + \cdots + M_I^* M_I.$$

Introduction

• Suppose we compute cohomology of G from

$$\cdots \to (\mathbb{Z}G)^{k_{i-1}} \xrightarrow{d_{i-1}} (\mathbb{Z}G)^{k_i} \xrightarrow{d_i} (\mathbb{Z}G)^{k_{i+1}} \to \cdots$$

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TFAE for G and i > 1:

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TFAE for G and i > 1:

• Hⁱ vanish and Hⁱ⁺¹ are reduced.

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Theorem (Bader and Nowak, 2020)

TFAE for G and $i \ge 1$:

- Hⁱ vanish and Hⁱ⁺¹ are reduced.
- $\Delta_i \lambda I = SOS$ for some $\lambda > 0$.

How to get the matrices d_i ?

Introduction

Fox calculus





Fox calculus 0000

Definition of Fox derivatives

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$$G = \langle s_1, \ldots, s_n | r_1, \ldots, r_m \rangle$$

Fox calculus 0000

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Definition (Fox, '50s)

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The differentials $\frac{\partial}{\partial s_i}: \mathbb{R}F_n \to \mathbb{R}G$, $F_n = \langle s_1, \dots, s_n \rangle$ are defined by:

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Definition (Fox, '50s)

The Fox derivatives are the elements $\frac{\partial r_i}{\partial s_i} \in \mathbb{R}G$.







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$$\bullet \ d_0 = \begin{bmatrix} 1 - s_i \\ \vdots \\ 1 - s_n \end{bmatrix}$$

Fox calculus 0000

Computing cohomology

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Theorem (Lyndon, '50s)

The cohomology $H^*(G, V)$ is the cohomology of the following complex:

$$0 \to V \xrightarrow{d_0} V^n \xrightarrow{d_1} V^m \to \cdots$$

Geometric interpretation

Fox calculus

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Geometric interpretation

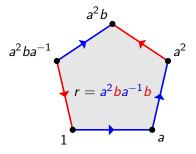
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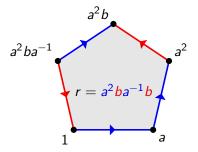
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Geometric interpretation

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$$\bullet \ 0 \to V \xrightarrow{\begin{bmatrix} 1-a \\ 1-b \end{bmatrix}} V^2 \xrightarrow{\begin{bmatrix} 1+a-a^2ba^{-1} & a^2+a^2ba^{-1} \end{bmatrix} = d_1} V$$

Spectral gap for the first Laplacian of $SL_3(\mathbb{Z})$

Laplacian spectral gaps

(joint work with M. Kaluba and P. Nowak)



• When $M \in M_n(\mathbb{R}G)$ is an SOS?

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- $y = I_n \otimes x \in M_{mn,n}(\mathbb{R}G)$, x column with half-basis for M

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Introduction

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Lemma

Introduction

M = SOS iff there exists $P \succeq 0$ such that $M = y^*Py$.

• Convex optimization for $M = \Delta_1 - \lambda I$:

maximize:

 $M_{i,i}(g) = \langle \delta_{i,i} \otimes \delta_g, P \rangle,$ subject to: $P \succ 0$.

Reducibility of the second cohomology for $SL_3(\mathbb{Z})$

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• We use the following presentation of $SL_3(\mathbb{Z})$:

$$SL_3(\mathbb{Z}) = \langle \{E_{i,j}\} | [E_{i,j}, E_{i,k}], [E_{i,j}, E_{j,k}] E_{i,k}^{-1},$$
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Theorem (Kaluba, M., Nowak)

For $SL_3(\mathbb{Z})$ the expression $\Delta_1 - \lambda I$ is an SOS for any $\lambda < 0.32$.

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Theorem (Kaluba, M., Nowak)

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Corollary

Introduction

The first cohomology of $SL_3(\mathbb{Z})$ vanishes, and the second is reduced.



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$$G = (V, E)$$

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• Cheeger constant:
$$h(G) = \inf_{1 \le \#A \le \#V/2} \frac{\#E(A,V \setminus A)}{\#A}$$

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- $SL_3(\mathbb{Z})$: spectral gap \Rightarrow "CW-expanders"

Thank you for attention!

Laplacian spectral gaps